

# Dynamics of electrically driven sub-nanosecond switching in Vanadium dioxide

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**Abstract** — The switching dynamics of electrically driven insulator-to-metal transition (IMT) and metal-to-insulator transition (MIT) in vanadium dioxide are investigated. The transient response of time domain measurements are modeled using a domain based 2-D heterogeneous resistive network, taking into account local electronic potential and local Joule heating. It reveals, the switching time is dominated by a spatially non-uniform percolation of the metallic phase during the IMT driven by electro-thermal forces. We demonstrate an IMT switching time of 793ps in scaled VO<sub>2</sub> devices and project IMT and MIT switching speed for scaled devices.

## I. INTRODUCTION

Vanadium dioxide (VO<sub>2</sub>) exhibits an insulator-to-metal transition (IMT) at 340K in bulk, characterized by up to five orders of magnitude change in resistivity [1]. The ability to electrically induce a phase transition implies the opportunity of VO<sub>2</sub> in abrupt electronic switches as selectors for three dimensional cross-point memories, steep slope Phase-FETs (Fig. 1(b)), and coupled oscillator network [2], [3]. In this work, we explore the fundamental dynamics of the reversible phase transition in two terminal VO<sub>2</sub> devices as a function of dimensions, with the goal to optimize its high speed switching capability during both IMT and MIT.

## II. CHARACTERIZATION AND RESULTS

Fig. 2 illustrates the effect of varying pulse amplitudes (V<sub>IN</sub>) and pulse widths (PW) on the speed of the IMT (τ<sub>IMT</sub>) and metal-to-insulator transition (MIT) (τ<sub>MIT</sub>). Transient measurements show that, for small V<sub>IN</sub>, the IMT occurs in sets of multiple abrupt events (τ<sub>IMT1</sub>). This is attributed to a spatially non-uniform transition characterized by regions of phase coexistence experimentally measured using spatially resolved microwave impedance spectroscopy [4]. We have developed a 2-D heterogeneous resistive network (Fig 3(a)) to explain the empirical results quantitatively. The VO<sub>2</sub> device is described as a rectangular grid of domains (n=45;m=84) each independently capable of undergoing IMT or MIT. Domains are allowed to undergo transition based on the local potential drop, ΔV, across it and local temperature. The probability of a potential dependent transition is calculated from equations (1)-(3) [4].

$$\Delta V = ((V_1 - V_3)^2 + (V_2 - V_4)^2)^{1/2} \quad (1)$$

$$P_{IMT} = e^{-(E_B - q\Delta V)/kT} \quad (2)$$

$$P_{MIT} = e^{-(E_B - E_C)/kT} \quad (3)$$

The probability of a temperature initiated transition is calculated based on the power generated due to the local current flow from equation (4) [5].

$$\frac{\partial T_{n,m}}{\partial t} c = P_{n,m} - \kappa \left( 4T_{n,m} - \sum_i^{1st\ neighbors} T_i \right) + h_d (T_{ext} - T_{n,m}) \quad (4)$$

The measured and simulated switching results, for low and high V<sub>IN</sub>, are compared in Figs. 3(b)-(c) & Figs. 4(a)-(b). The model captures the discontinuous switching observed experimentally for V<sub>IN</sub>=1.4V and captures the faster single abrupt switching for V<sub>IN</sub>=2.1V. The respective domain state and temperature maps of the channel are shown in Figs. 3(d) & 4(c). Fig. 5 shows the device scaling trends for τ<sub>IMT</sub>. The reduction in device area reduces the total area over which the IMT must propagate and improves the switching performance. Fig. 6 shows the device scaling normalized at V<sub>IN</sub>=2.2V. 793 picosecond switching is observed in a L<sub>VO2</sub>=100nm & W<sub>VO2</sub>=300nm device (Fig. 7). The role of joule heating on τ<sub>MIT</sub> is highlighted in Fig. 8, where increasing V<sub>IN</sub> and PW causes increased and prolonged joule heating raising the local domain temperatures and prolonging τ<sub>MIT</sub>. Due to the conflicting dependence of τ<sub>IMT</sub> and τ<sub>MIT</sub> on V<sub>IN</sub> an optimal operating point exists for a complete cycle of switching. The trade off is shown in Fig. 9 where low V<sub>IN</sub> requires longer pulse widths due to the longer τ<sub>IMT</sub> and higher voltages cause excessive power generation in the channel. Using the 2-D heterogeneous resistive network we capture and predict the scaling trends for the total switching cycle as the device dimensions are reduced (Fig. 10).

## III. CONCLUSION

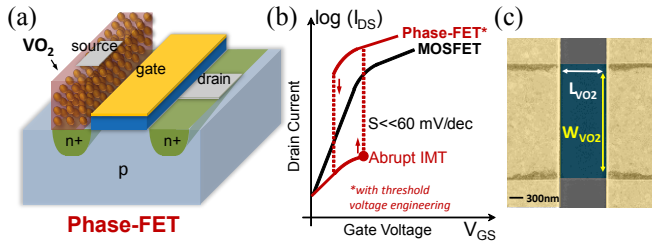
In summary, we experimentally demonstrate sub-nanosecond (793ps) switching in VO<sub>2</sub> through dimensional scaling. A 2-D model quantitatively explains the electro-thermal IMT in the high and low voltage regimes, while the MIT is found to be limited by joule heating. We show scaling L<sub>VO2</sub>, W<sub>VO2</sub>, input voltage pulse width and amplitude, minimizes the area over which the IMT must propagate and can limit joule heating improving both τ<sub>IMT</sub> and τ<sub>MIT</sub>. This demonstrates a design space and pathway toward realizing high-speed abrupt switches and oscillatory devices in VO<sub>2</sub>.

## ACKNOWLEDGEMENTS

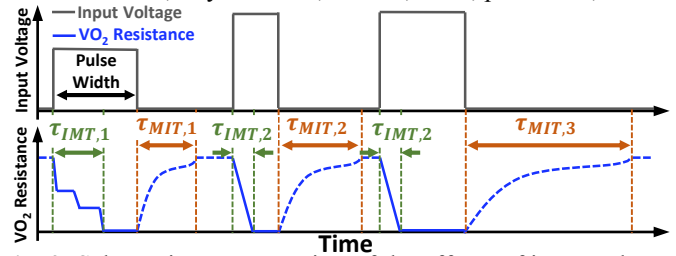
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## References:

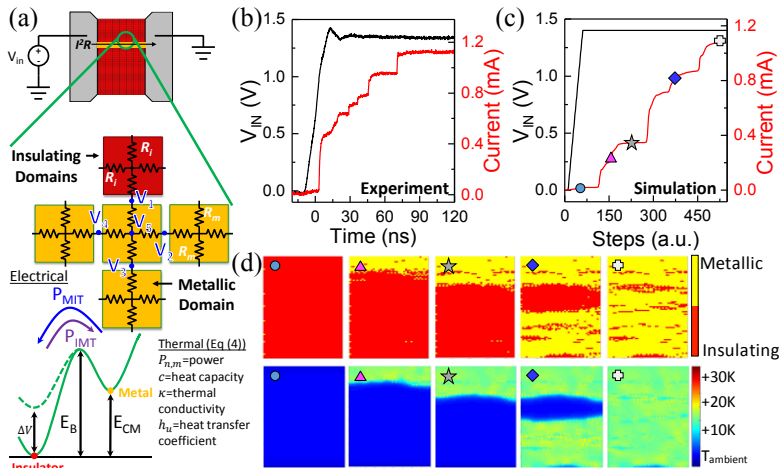
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 [2] N. Shukla *et al.*, Nat. Commun., vol. 6, p. 7812, 2015. [4] H. Madan *et al.*, ACS Nano, vol. 9, no. 2, pp. 2009-17, 2015.  
 [5] P. Stolar *et al.*, Phys. Rev. B, vol. 90, no. 4, p. 045146, 2014.



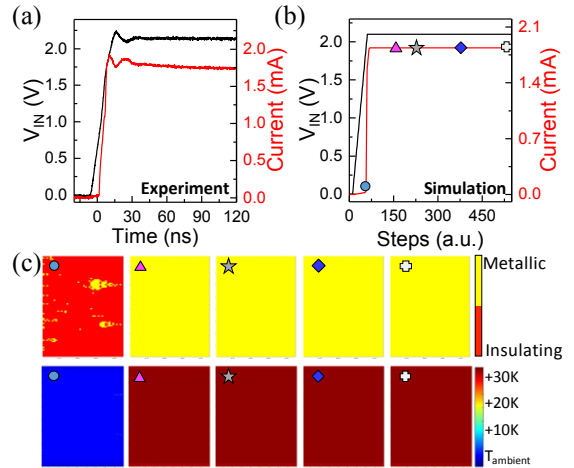
**Fig. 1.** (a) Phase-FET schematic showing integrated structure. (b) Transfer characteristics comparing MOSFET and Phase-FET. (c) SEM image of a two-terminal VO<sub>2</sub> device used to characterize VO<sub>2</sub> switching speed.



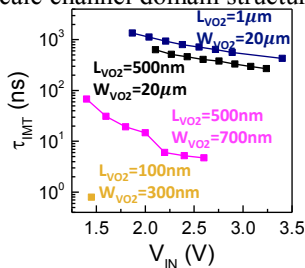
**Fig. 2.** Schematic representation of the effects of input voltage pulse on  $\tau_{IMT}$  and  $\tau_{MIT}$ . Higher  $V_{IN}$  results in increased local potential drops and joule heating across the nano-domain structure enhancing the speed of the IMT transition.



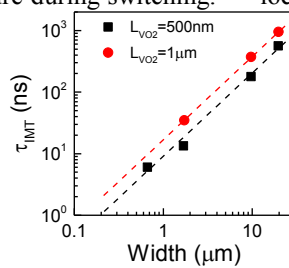
**Fig. 3.** (a) 2-D heterogeneous resistive network used to model the filamentary nature of conduction in VO<sub>2</sub>. (b)(c) Measured and simulated switching transient at  $V_{IN}=1.4V$ . (d) Corresponding nanoscale channel domain structure and temperature during switching.



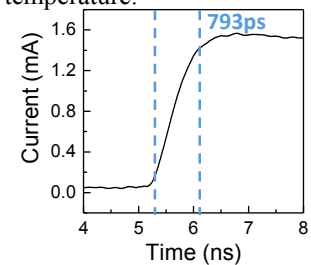
**Fig. 4.** (a) Measured waveform for  $V_{IN}=2.1V$ . (b) Simulated switching for  $V_{IN}=2.1V$  and (c) corresponding channel domain structure and locally computed temperature.



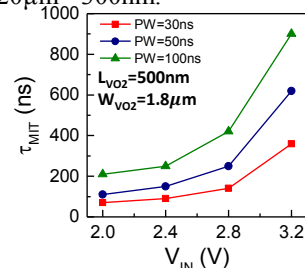
**Fig. 5.** Measured  $\tau_{IMT}$  as a function of input bias for varying device sizes; lengths from 1 $\mu m$  - 100nm and widths from 20 $\mu m$  - 300nm.



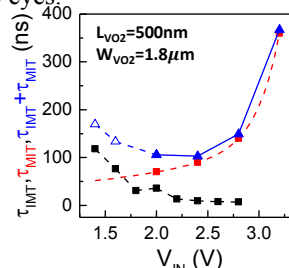
**Fig. 6.**  $\tau_{IMT}$  scaling trends for  $W_{VO_2}$  and  $L_{VO_2}$  normalized to  $V_{IN}=2.2V$ . Red and black broken lines serve as a guide to the eyes.



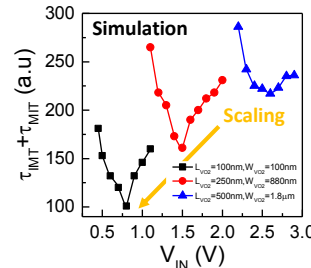
**Fig. 7.** Sub-nanosecond switching (793ps) for device size:  $L_{VO_2}=100nm$ ,  $W_{VO_2}=300nm$  at  $V_{IN}=1.45V$ .



**Fig. 8.**  $\tau_{MIT}$  as a function of input bias. Increasing  $V_{IN}$  or PW causes greater joule heating within the VO<sub>2</sub> device lengthening the thermal dissipation time.



**Fig. 9.** Measured  $\tau_{IMT} + \tau_{MIT}$  as a function of  $V_{IN}$  (PW=30ns). An optimal operating point exists due to differing dependence of  $\tau_{IMT}$  and  $\tau_{MIT}$  on  $V_{IN}$ .



**Fig. 10.** Simulated scaling trends for  $\tau_{IMT} + \tau_{MIT}$  highlighting the benefit coming from area, pulse width, and switching voltage reduction.